

BI-DIRECTIONAL FOUR-MODE CLUTCH

BACKGROUND OF THE INVENTION

1. Field of the Invention

[0001] The present invention relates, generally to bi-directional overrunning clutch assemblies and, more specifically, to an actively controlled, bi-directional, overrunning clutch assembly having four modes of possible operation for use in motor vehicle driveline components such as transmissions, transfer cases, differentials and the like.

2. Description of the Related Art

[0002] Generally speaking, land vehicles require three basic components. These components include a power plant (such as an internal combustion engine), a power train and wheels. The power train's main component is typically referred to as the "transmission." Engine torque and speed are converted in the transmission in accordance with the tractive-power demand of the vehicle. Transmissions include one or more gear sets which may include an inner gear, intermediate planet or pinion gears that are supported by their carriers, and outer ring gears. Various components of the gear sets are held or powered to change the gear ratios in the transmission. In addition to such planetary gear sets, driveline components may further include multi-disc friction devices that are employed as clutches or brakes. The multi-disc pack clutch is a friction device that is commonly employed as a holding mechanism in a transmission, transfer case or differential or the like. In addition, multi-disc friction devices also find use in industrial applications, such as wet brakes, for example, to brake the wheels on earth-moving equipment.

[0003] The multi-disc pack clutch or brake assembly has a clutch sub-assembly including a set of plates and a set of friction discs that are interleaved between one another. The plates and

friction discs are bathed in a continual flow of lubricant and in “open pack” mode normally turn past one another without contact. The clutch or brake assembly also typically includes a piston. When a component of a gear set is to be held, as for example during a particular gear range, a piston is actuated so as to cause the plates and friction discs to come in contact with respect to one another. In certain applications, it is known to employ several multi-disc pack clutch devices in combination to establish different drive connections throughout the transmission, transfer case, or differential to provide various gear ratios in operation, or to brake a component.

[0004] When the discs are not engaged, there often remains a differential rotational speed between the drive and driven members that the clutch or brake bridges. Relative rotation between the friction discs and the plates during open-pack mode creates drag. This condition results in parasitic energy losses, reduces the efficiency of the transmission, transfer case or differential, and ultimately results in lower fuel efficiency.

[0005] In addition to multiple friction devices, one-way clutches are frequently employed in transmissions, transfer cases, and differentials to selectively transmit torque in one rotational direction, but not in the opposite rotational direction. To this end, one-way clutches typically include an inner race, an outer race, and an engagement mechanism disposed therebetween. The engagement mechanism is operable to lock the inner and outer races together thereby transmitting torque in one relative direction. The engagement mechanism is further operable to allow freewheeling rotation between the inner and outer races in the opposite rotational direction. Engagement mechanisms commonly used in one-way clutches of the related art include pawls, sprags, and rollers. A cage, along with biasing members, such as springs, are also sometimes employed to retain the pawls, sprags, or rollers between the inner and outer races as well as to selectively assist in the change of

operational modes between torque translation and freewheeling actuation of the clutch, depending on the direction of rotation between the inner and outer races.

[0006] As noted above, one-way clutches of this type have been employed in numerous applications in transmission, transfer cases, and differentials. For example, one-way clutches have been employed in conjunction with multiple friction clutches and planetary gear sets to effect low and reverse gear ratios in conventional transmissions. While this arrangement has worked well for its intended purpose, some disadvantages remain. For example, the friction clutch remains a source of significant parasitic losses due to inherent drag between the friction plates when the clutch is operating in “open pack” mode. Still, the clutch is necessary for providing the proper holding torque in low and reverse gears. Accordingly, there remains a need in the art for a mechanism that can provide the appropriate holding torque for both low and rear gears in the transmission and yet results in less parasitic losses which are presently attributable to the multiple plate friction clutch used for this purpose. In addition, there is a need in the art for a device that continues to perform the functions of the one-way clutch as described above, particularly where the output speed of the transmission exceeds the input speed resulting in engine compression braking.

[0007] One-way clutches have also been employed in transfer cases that provide full time, part time, and “on demand” four wheel drive (4WD) capabilities. In these situations, the one-way clutch is typically disposed between the primary driveline and the secondary driveline. When the primary drive line attempts to over speed the secondary drive line, as will occur, for example, where the rear wheel is supported on a slick surface, such as ice and is spinning and the front wheels are solidly supported, the one-way clutch engages and transfers torque to the slipping wheel. In this way, 4WD is achieved, but in this case, only under circumstances that require it.

[0008] The use of a one-way overrunning clutch to selectively provide drive torque to a secondary driveline upon primary wheel slip has not, however, become a popular solution to part time 4WD vehicle requirements because of one problem: the clutch remains disengaged or inactive when reverse gear is selected unless, of course, the secondary driveline attempts to over speed the primary driveline. Thus, in a situation frequently requiring 4WD, that is, when the vehicle may need to be rocked or simply backed over terrain, a 4WD configuration utilizing a one-way overrunning clutch will simply not provide 4WD operation. This is a significant drawback of this clutch configuration.

[0009] Partially in response to this problem, bi-directional overrunning clutches have been proposed in the related art for use in these circumstances. These bi-directional overrunning clutch assemblies typically employ an inner race, an outer race, and a plurality of rollers as the engagement mechanism disposed therebetween. An actuator is employed to bias the rollers in one direction or another to allow freewheeling or torque translation in either rotational direction depending upon the position of the rollers. However, and while they appear to present a solution to certain problems identified above, bi-directional overrunning clutches have not been widely employed in transmission, transfer cases, and differentials of the related art. They are relatively mechanically complex and therefore generally more expensive than conventional one-way clutches. In addition, many of the designs considered in the related art simply do not operate at an acceptable level that meets the standards of today's sophisticated driving public.

[0010] Accordingly, there remains a need in the art for a bi-directional overrunning clutch assembly that can provide torque translation in either rotational direction as well as one that may be

employed as a substitute for conventional multi-disc friction devices presently known in the related art.

SUMMARY OF THE INVENTION

[0011] The disadvantages of the related art are overcome in a bi-directional overrunning clutch assembly of the present invention. The bi-directional clutch assembly includes an inner race, an outer race and an engagement mechanism that is supported therebetween. The engagement mechanism includes a first set of pawls and a second set of pawls operatively supported between said inner and outer races. In addition, the clutch assembly includes at least one actuating cam disposed adjacent the inner and outer races and including a plurality of disengagement portions as well as a plurality of engagement portions. The engagement and disengagement portions cooperate with the first and second pawls to (1) selectively disengage the first and second pawls to provide freewheeling relative rotation between the inner and outer races; (2) to selectively actuate at least one pawl of the first set of pawls so that torque is translated in a first rotational direction but allowing freewheeling relative rotation between the inner and outer races in a second rotational direction that is opposite to the first rotational direction; (3) to selectively actuate at least one pawl of the second set of pawls so that torque is translated in the second rotational direction opposite to the first rotational direction but allowing freewheeling relative rotation in the first rotational direction; and (4) to selectively actuate at least one pawl of the first and second sets of pawls so that torque is translated between the inner and outer races in both of the first and second rotational directions.

[0012] The bi-directional over-running clutch assembly of the present invention is particularly adapted for use in an automotive transmission having at least one shaft and at least one gear set that is operatively coupled to the shaft to provide low and reverse gear ratios. The

transmission assembly includes a transmission casing for supporting the shaft and the gear set of the transmission assembly. The gear set includes a sun gear operatively coupled to a source of torque in the transmission assembly, a ring gear mounted for rotation about the sun gear and a plurality of pinion gears. The pinion gears are supported by a carrier for rotation about the sun gear and between the ring gear and the sun gear. The carrier is operatively coupled to the shaft. The bi-directional clutch assembly has an inner race that is operatively coupled to the ring gear of the gear set. The outer race is operatively coupled to the transmission casing and an engagement mechanism is supported between the inner and outer races. The engagement mechanism includes a first set of pawls and a second set of pawls that are operatively supported between the inner and outer races. In addition, the bi-direction over-running clutch assembly includes at least one actuating cam disposed adjacent the inner and outer races and including a plurality of disengagement portions as well as a plurality of engagement portions. The engagement and disengagement portions cooperate with the first and second pawls (1) to selectively disengage the first and second pawls to provide freewheeling relative rotation between the inner and outer races; (2) to selectively actuate at least one pawl of the first set of pawls so that torque is translated in a first rotational direction when the transmission assembly is in low gear but allowing freewheeling relative rotation between the inner and outer races in a second rotational direction that is opposite to the first rotational direction when the transmission assembly is in any higher gear; (3) to selectively actuate at least one pawl of the second set of pawls so that torque is translated in the second rotational direction opposite to the first rotational direction when the transmission assembly is in reverse gear but allowing freewheeling relative rotation in the first rotational direction when the transmission assembly is in any gear greater than first gear; and (4) to selectively actuate at least one pawl of the first and second sets of pawls so that torque is

translated between the inner and outer races in both of the first and second rotational direction to provide engine braking.

[0013] Thus, one advantage of the bi-directional overrunning clutch assembly of the present invention is that it provides four distinct modes as illustrated in Figures 2 - 5. In this way, the bi-directional overrunning clutch assembly of the present invention may be employed as a component of an automotive driveline in a transmission, transfer case, or differential to eliminate other components while maintaining the requisite functionality.

[0014] Another advantage of the bi-directional overrunning clutch assembly of the present invention is that when it is used in connection with providing low and reverse gear ratios in the representative transmission illustrated in Figure 6, at least one multi-disc friction clutch and a one-way clutch may be eliminated. In this way, the clutch assembly of the present invention reduces parasitic energy loss, improves operational efficiency, and reduces cost.

[0015] Another advantage of the bi-directional overrunning clutch of the present invention is that it may be employed in a transmission to provide the important engine braking effect that can occur when the speed of the transmission output shaft exceeds the speed of the input to any given planetary gear set.

[0016] Other objects, features and advantages of the present invention will be readily appreciated as the same becomes better understood after reading the subsequent description taken in connection with the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

[0017] Figure 1 is an exploded view of the bi-directional overrunning clutch assembly of the present invention;

[0018] Figure 2 is an enlarged partial side view of the bi-directional overrunning clutch assembly of the present invention illustrating one mode of operation where both sets of pawls are disengaged such that the clutch may freewheel in both directions;

[0019] Figure 3 is an enlarged partial side view of the bi-directional overrunning clutch assembly of the present invention illustrating another mode of operation where every other pawl is free to engage so as to provide torque translation in one direction but allow freewheeling movement in the opposite rotational direction;

[0020] Figure 4 is an enlarged partial side view of the bi-directional overrunning clutch assembly of the present invention illustrating a third mode of operation where every other pawl is free to engage to provide torque translation in the opposite rotational direction as illustrated in Figure 3 but to allow freewheeling movement between the inner race and the outer race in the rotational direction opposite to that in which torque is translated in this mode;

[0021] Figure 5 is an enlarged partial side view of the bi-directional overrunning clutch assembly of the present invention illustrating a fourth mode of operation wherein both sets of pawls are free to engage so that the inner and outer races are locked relative to each other and torque is translated in both rotational directions;

[0022] Figure 6 is a schematic diagram depicting a transmission illustrating one possible use of the bi-directional overrunning clutch assembly of the present invention in connection with providing low and reverse gear ratios; and

[0023] Figure 7 is a schematic representation of the bi-directional overrunning clutch assembly employed in conjunction with a planetary gear set to provide low and reverse gear ratios in the transmission of Figure 6.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT(S)

[0024] The bi-directional overrunning clutch assembly of the present invention is generally indicated at 10 in Figures 1 - 5, where like numerals are used to designate like structure throughout the drawings. The various subcomponents of the clutch assembly 10 are illustrated in the exploded view of Figure 1 and the four operational modes are illustrated in the partial side views of Figures 2 - 5. The clutch assembly 10 is particularly adapted for use as a component of drivelines of land-based vehicles, such as in transmissions, transfer cases, differentials and the like. Accordingly, one application for the clutch assembly 10 of the present invention is shown in connection with a transmission which is schematically illustrated in Figures 6 and 7. However, those having ordinary skill in the art will appreciate that the clutch assembly of the present invention may be employed in numerous applications, whether or not the application takes advantage of all four operational modes of the clutch assembly as discussed below.

[0025] Referring now to Figure 1, the clutch assembly 10 of the present invention includes an inner race, generally indicated at 12, an outer race, generally indicated at 18, and an engagement mechanism, generally indicated at 15, that is supported between the inner and outer races. The engagement mechanism 15 includes a plurality of pockets, generally indicated at 20 and a corresponding plurality of pawls, generally indicated at 24. In addition, the engagement mechanism includes a plurality of teeth, generally indicated at 14. In the preferred embodiment illustrated in figures, the teeth 14 are formed on the outer circumference 16 of the inner race. Roots 17 are defined between adjacent teeth 14. On the other hand, the plurality of pockets 20 are formed on the inner circumference 22 of the outer race. However, those having ordinary skill in the art will appreciate from the description that follows that the teeth may be formed on the outer race and the pockets may be formed on the inner race without departing from the scope of the present invention.

[0026] As noted above, the clutch assembly 10 is bi-directional. Thus, with reference to Figures 2 - 5, the plurality of pockets 20 will include first and second sets of pockets 20A and 20B. Each pocket in a given set is located adjacent to a pocket from the other set. Furthermore, each pocket in the first set is oriented in an opposite direction relative to an adjacent pocket of the second set about the inner circumference of the outer race. Similarly, the plurality of pawls 24 include first and second sets of pawls 24A and 24B. The two sets of pawls 24A and 24B correspond to the two sets of pockets 20A and 20B. Each of the pawls 24 is moveably supported in a corresponding set of pockets 20 such that each pawl from the first set 24A is adjacent to a pawl from the second set 24B. In addition, each pawl 24A in the first set is oriented in an opposite direction relative to an adjacent pawl 24B from the second set. Thus, the clutch assembly 10 of the present invention includes essentially two sets of pawls 24 that are oriented in opposite directions. The first set of pawls 24A acts to translate torque between the inner and outer races in one rotational direction. This occurs when at least one pawl 24A of the first set of pawls is disposed in its engaged position. The second set of pawls 24B acts to translate torque between the inner and outer races in the opposite rotational direction when at least one pawl 24B of the second set of pawls is disposed in its engaged position. The first set of pawls 24A may be designated as forward pawls. Engagement of one of the opposing, or second set of pawls 24B will allow for reverse movement and may therefore be designated as the reverse pawls. It should be appreciated that the designating of one of the two sets of pawls 24 as "first" or "forward" and the other set as "second" or "reverse" is merely a relative designation dependant on the application in which the clutch is employed (e.g. transmission or transfer case) and may relate to the relative rotational direction that achieves either a forward or reverse movement of the vehicle. Those having ordinary skill in the art will appreciate from the description that follows that the two sets of pawls 24A and 24B are identical and are supported about the inner diameter of

the outer race so that adjacent pawls are opposed to one another to achieve the bi-directional function of the clutch. The specific structure of the pawls and pockets as well as the interaction of the engagement mechanism between the inner and outer races that provides this functionality will be discussed in greater detail below.

[0027] While the pawls may have any suitable geometric shape, as illustrated, for example, in Figures 2 - 5, the pawls 24 have a generally triangular shape when viewed from the side. As noted above, the pawls 24 are received in the pockets 20 formed in the inner diameter 22 of the outer race 18 and are supported in circumferentially spaced orientation about the rotational axis A of the clutch assembly 10. In addition, as best shown in Figure 1, each pawl 24 defines a longitudinal axis that extends in the direction of the rotational axis A. Each pawl 24 has a nose portion 28 and a fulcrum portion 30 formed thereon. The fulcrum portion 30 is adapted to provide pivoting motion relative to a corresponding surface 31 defined by the pockets 20. A biasing member 32 is also captured in a special axially extending recess 34 formed in each pocket 20. The biasing member 32 provides a biasing force between the outer race 18 and the pawl 24 to bias the nose portion 28 of the pawl 24 into engagement with a torque-translating tooth 14 formed on the outer diameter 16 of the inner race 12. In the preferred embodiment, the biasing member is a Z-shaped spring having a longitudinal axis which corresponds to the longitudinal axis of the associated pawl 24 and is disposed within the special recess 34 so as to be substantially parallel with the rotational axis A of the clutch assembly 10. However, those having ordinary skill in the art will appreciate that any number of biasing members known in the related art may be suitable for this purpose. Thus, within the context of this description of the preferred embodiment of the present invention, those having ordinary skill in the art will appreciate that the present invention is not limited in any way to the specific Z-shaped biasing member 32 illustrated and described herein.

[0028] As noted above, adjacent pawls 24 are oriented in opposite directions. Thus, each adjacent pawl 24 is supported by its associated pocket 20 such that the nose portion 28 of each adjacent pawl 24 is pointed, generally, in the opposite direction. More specifically, every other pawl 24 is disposed to selectively provide torque translation in opposite rotational directions as will be described in greater detail with respect to Figures 2 - 5.

[0029] The clutch assembly 10 further includes at least one actuating cam, generally indicated at 26. The actuating cam 26 is operatively disposed relative to the inner and outer races 12, 18 to actuate the engagement members 24 to provide four separate modes of operation between the inner and outer races 12, 18 of the clutch assembly 10. More specifically, and referring now to Figures 2 - 5, the cam is operable to (1) disengage the engagement members 24 to provide freewheeling between the inner and outer races 12, 18 in both rotational directions as shown in Figure 2; (2) to actuate the engagement members 24 so that torque is translated in one rotational direction but to allow freewheeling in the opposite rotational direction as shown in Figure 3; (3) to actuate the engagement members 24 so that torque is translated in a direction opposite to that in mode (2) above, but allow freewheeling in the rotational direction opposite to that in which torque is translated in this mode (Figure 4); and (4) to actuate the engagement members 24 so that the inner and outer races 12, 18 are locked relative to each other and torque is translated in both rotational directions (Figure 5).

[0030] Preferably, the clutch assembly 10 includes a pair of actuating cams 26 as best shown in Figure 1. The cams 26 may be disposed on either side of the inner and outer races 12, 18 or they may be nested with respect to each other and located on one side or the other of the clutch assembly. As noted above, each of the cams 26 may be selectively indexed to bring one or more pawls from one set of pawls 24 into an engaged or disengaged position. To this end, each actuating cam 26

includes a flat disc portion 27 having a plurality of disengagement portions 36 spaced about the outer periphery of the flat disc portion 27. The disengagement portions 36 are adapted to disengage every other pawl 24. More specifically, the disengagement portions 36 formed on one of the actuating cams define a first set of disengaging portions that cooperate with the first set of pawls 24A to move the first set of pawls 24A out of engagement between the inner and outer races of the clutch assembly. Similarly, the other actuating cam 26 includes a second set of disengagement portions that cooperate with the second set of pawls 24B to move the second set of pawls out engagement between the inner and outer races. Thus, when both actuating cams 26 are disposed in this orientation, they support each pawl 24 so that the pawls 24 cannot engage the teeth 14 formed on the outer diameter 16 of the inner race 12. In this disposition, the clutch assembly 10 may freewheel in either rotational direction as illustrated, for example in Figure 2.

[0031] In addition, the actuating cams 26 includes a plurality of engagement portions that are defined by sloping portions 40. More specifically, the plurality of engagement portions include a first set of sloping portions 40 that cooperate with the first set of pawls 24A to move at least one of the pawls of the first set into an engaged position so that torque is translated in the first rotational direction. Similarly, the plurality of engagement portions include a second set of sloping portions 40 formed on the other actuating cam 26 that cooperate with the second set of pawls 24B to move at least one of the pawls of the second set of pawls 24B into an engaged position so that torque is translated in a second rotational direction that is opposite from the first. In the embodiment illustrated here, each disengaged portion 36 is formed between adjacent sloping portions 40 on each assembly cam 26. Thus, when a given cam 26 is oriented such that the sloping portion 40 is disposed opposite a pawl 24, the biasing member 32 acts to move the nose portion 28 of the pawl 24 in the direction of the outer diameter 16 of the inner race 12 and into engagement with one of the

teeth 14 formed thereon. In this operative mode, torque is translated between the inner and outer races 12, 18 in one rotational direction or the other as illustrated in Figures 3 and 4. When the other cam 26 is actuated so that its disengagement portions 36 are disposed opposite the respective pawls 24, the clutch assembly 10 will freewheel in the opposite rotational direction as illustrated in Figures 3 and 4. On the other hand, when a sloping portion 40 of both actuating cams 26 is disposed opposite a corresponding pawl 24, the nose portion 28 of that pawl 24 is biased into engagement with a corresponding tooth 14 formed on the outer diameter 16 of the inner race 12. When at least one of the pawls from both sets of pawls 24 are engaged in this manner, the inner and outer races 12, 18 are locked together and torque is translated in both rotational directions as illustrated in Figure 5.

[0032] Each actuating cam 26 includes a plurality of outer rotational guides 42 located between adjacent sloping portions 40. The outer rotational guides 42 engage the inner radius 22 of the outer race 18 and thereby provide concentric stability of the actuating cam 26 relative to the outer race 18.

[0033] As will be clear from the discussion that follows, the bi-directional overrunning clutch assembly 10 of the present invention may be employed in any number of applications to provide one or more of the four operational modes described above. For example, the clutch assembly 10 may be employed to eliminate a multi-disc friction clutch as well as other components that are commonly used in transmissions, transfer cases, and differentials. In this way, the clutch assembly may result in a reduction of parasitic energy losses that are associated with the use of multi-plate friction disc clutches. When used in this way, the clutch assembly 10 of the present invention thereby results in reduced weight and a concomitant reduction in cost in the associated driveline component.

[0034] One representative example of an advantageous use of the bi-directional overrunning clutch assembly of the present invention is shown in connection with a transmission, schematically illustrated at 50 in Figure 6. The transmission 50 has a number of conventional components that are arranged to translate torque between a prime mover, such as an internal combustion engine (not shown) and the output of the transmission at various gear ratios. However, those having ordinary skill in the art will appreciate that the standard components of a transmission may be arranged in numerous ways to provide various gear ratios. Thus, the exact configuration of these components form no part of the present invention and are only discussed to better illustrate the salient features of the bi-directional overrunning clutch assembly 10 of the present invention.

[0035] To this end, the transmission 50 includes a torque converter, generally indicated at 52, and a plurality of multi-plate friction disc clutches 54, 56, 58, 60, 62 or similar mechanisms that serve as holding mechanisms or brakes to translate torque between the primary transmission input shaft 64 and the primary transmission output shaft 66 acting through a plurality of planetary gear sets 68, 70, and 72, as is commonly known in the art. The torque converter 52 includes an impeller assembly 74 operatively connected for rotation with the torque input member 76 from the internal combustion engine. A turbine assembly 78 is fluidly connected in driven relationship with the impeller assembly 74. The torque converter 52 also includes a stator assembly 80. These assemblies together form a substantially toroidal flow passage for kinetic fluid in the torque converter 52. Each assembly includes a plurality of blades or vanes that act to convert mechanical energy into hydrokinetic energy and back to mechanical energy. The stator assembly 80 of a conventional torque converter is locked against rotation in one direction but is free to spin about an axis in the direction of rotation of the impeller assembly 74 and the turbine assembly 78. A one-way clutch 82 is often employed for this purpose. When the stator assembly 80 is locked against rotation, the torque is

multiplied by the torque converter. During torque multiplication, the output torque is greater than the input torque for the torque converter 52. In addition, conventional torque converters often employ clutches 84 interposed between the torque input member 76 and the turbine assembly 78 which are engaged and “lock up” at higher speed ratios (speed output over speed input). When the clutch 84 is locked up, there is a direct torque translation between the torque input member 76 and the transmission 50 through the turbine assembly 78.

[0036] In the particular transmission 50 illustrated in Figure 6, an underdrive clutch 54, overdrive clutch 56, reverse clutch 58, fourth gear brake 60, and second gear brake 62 are employed as holding mechanisms to translate torque from the primary transmission input shaft 64 to various ones of the planetary gear sets 68, 70, and 72, as the case may be. In turn, each of the planetary gear sets include a sun gear operatively coupled to one of the clutches identified above, a ring gear disposed about the respective sun gear, and a plurality of pinion or planetary gears disposed in meshing relationship between the respective sun and ring gears.

[0037] In the representative embodiment illustrated herein, the bi-directional overrunning clutch assembly 10 of the present invention is employed in connection with the planetary gear set 72 which is used to provide low and reverse gear ratios. This application is schematically illustrated in Figure 7. In this case, torque is provided from the underdrive clutch 54 to the sun gear 86 that is splined to the shaft 88. For a low gear, such as first gear, the actuation cam 26 is indexed such that the bi-directional overrunning clutch assembly 10 is operating in the mode illustrated in Figure 3. In this application, the outer race 18 is grounded to the transmission case 90 through a reaction member. Input speed is thus geared down through the pinion gears 92 supported on the carrier 94 and from the carrier 94 to the transmission output shaft 66. In this way, a low gear ratio is effected at the output shaft 66 of the transmission 50. On the other hand, the clutch 10 is capable of

freewheeling in the opposite rotational direction. The bi-directional overrunning clutch assembly 10 of the present invention thus serves the same purpose as both the multi-disc friction clutch (that it replaces) plus the one-way clutch commonly employed for this purpose. Parasitic losses and the resultant reduction in fuel efficiency due to the multi-disc friction clutch are concomitantly eliminated. In addition to reducing parasitic losses, the bi-directional overrunning clutch assembly employed in connection with low and reverse gears also provides an important engine braking function. This may occur, for example, in manual first gear when the pawls 24 are engaged in the forward position as illustrated in Figure 5 and the operator has his foot in the throttle of the internal combustion engine. In this operative mode, torque is translated from the inner race 12 to the transmission case 90. However, in a “lift foot” condition, the inner race 12 shifts and the reverse pawls 24 are engaged. In this operative mode, the wheels of the automobile drive through the transmission providing torque to the engine. The engine thus acts as a brake on the vehicle.

[0038] When reverse gear is selected, the reverse clutch 58 is engaged and torque is translated to the ring gear 96 of the gear set 72 through the gear sets 68 and 70. In addition, the actuation cam 26 is indexed to the mode illustrated in Figure 4 via an actuator (electromagnetic, hydraulic, or otherwise) schematically illustrated at 98 in Figure 7. In this operational mode, the clutch 10 translates torque in a direction opposite to that illustrated in Figure 3, but allows freewheeling in the rotational direction opposite to that in which torque is translated in this mode (counterclockwise as illustrated in Figure 4).

[0039] Alternatively, in reverse gear, the bi-directional overrunning clutch 10 may be operated in the mode illustrated in Figure 5 wherein both sets of pawls 24 are locked to provide torque translation in either direction. Engine braking as described above may also be effected in reverse gear when the bi-directional overrunning clutch is operated in the mode illustrated in Figure

5. In the remaining gears 2 - 4 of the transmission illustrated in Figure 6, both of the actuation cams 26 are indexed to disengage both sets of pawls 24 so that the clutch 10 freewheels in both rotational directions.

[0040] Thus, in one representative example, the bi-directional overrunning clutch assembly 10 facilitates the removal of at least one multi-disc friction device as well as the one-way clutch typically associated with low and reverse gears thereby eliminating the parasitic losses associated with the friction clutch. In addition, the bi-directional overrunning clutch 10 still provides the important engine braking effect that can occur when the speed of the transmission output shaft exceeds the speed of the input to the planetary gear set 72 as illustrated in the representative transmission 50 of Figure 6.

[0041] The invention has been described in an illustrative manner. It is to be understood that the terminology which has been used is intended to be in the nature of words of description rather than of limitation. Many modifications and variations of the invention are possible in light of the above teachings. Therefore, within the scope of the appended claims, the invention may be practiced other than as specifically described.